# StarTracker In-studio Optical Camera Tracking System

Mo-sys

VISION IN MOTION



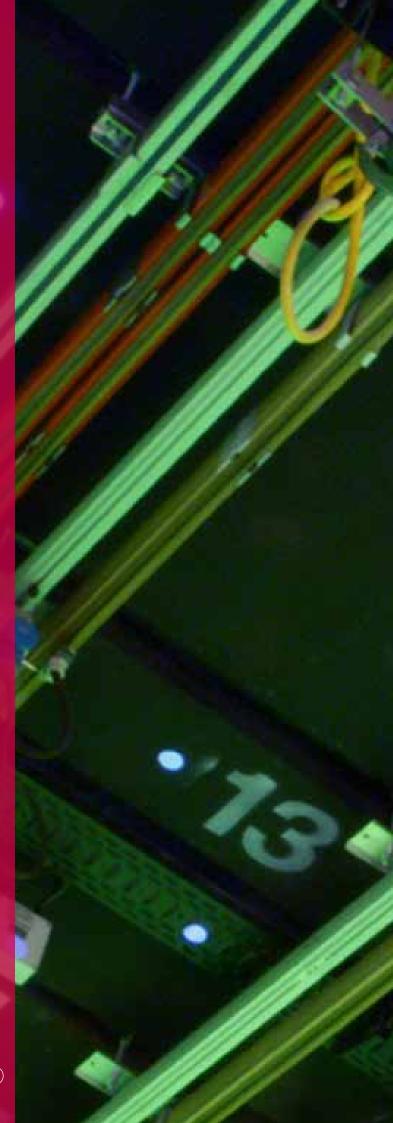


# Absolute tracking for film and broadcast

- Professional camera tracking StarTracker is intended for professional broadcast and film applications with studios up to 20m in height
- Unrivalled tracking accuracy –
   Mo-Sys StarTracker does not drift.
   Tracking remains accurate and there
   is no need for time-consuming and
   costly daily recalibration
- Compatible with digital markers (NEW) – StarTracker is fully compatible with Brompton digital markers. This is useful when working in LED volumes with ceiling panels

"As the top optical tracking system, Startracker is our choice for our studios and we've been impressed with the system's ease of use and low latency. Its proved itself to be a very robust and reliable tracking system and that's what our clients expect when they use our facilities."

Dan Hamill, Co-founder and Commercial Director at 80six





# Key Features

### **In-studio optical camera tracking**

- Robust tracking Far-reaching 120-degree field of view optical tracking offers maximum freedom of movement. The camera can be pointed almost straight down and StarTracker will maintain accurate tracking
- Resilience and reliability StarTracker is unaffected by powerful studio lighting. Creative lighting changes are possible because StarTracker uses a different spectrum of light to track. Mo-Sys retro-reflective "stars" can be applied randomly above the lighting grid and do not restrict the studio lights in any way
- Excellent synchronisation StarTracker enables fast camera movement to keep talent perfectly framed while maintaining accurate AR and VR asset positioning
- Autonomous operation once calibrated StarTracker works without requiring an operator, minimising the cost of operation
- 6-axis tracking with lens zoom and focus –
  precision blending of photo-realistic 3D virtual
  graphics with the real world, delivering an immersive
  mixed reality experience





### **Patented Technology**

- Unique retro-reflective markers StarTracker tracks from a random constellation of retro-reflective markers mounted to the ceiling or floor
- Wired or wireless operation –
   particularly useful in live broadcast,
   wireless operation can be utilised to
   provide Steadycam operators with
   maximum freedom
- Largest installed base of any professional camera tracking vendor – trusted by broadcasters, OEM manufacturers, major motion films, events companies, and enterprises across the world. Multiple re-orders from broadcasters further validate the system
- Integrated by OEM partners:
   Vinten, Cartoni, Shotoku, Grass
   Valley, Panasonic no other camera
   tracking vendor is utilised and trusted
   by so many OEM vendors
- Patented technology Mo-Sys pioneered marker based camera tracking, and as the leader in the space continues to develop the technology
- Auto Aligner rapid studio calibration technology, minimising setup time prior to shooting
- Custom lens profiling StarTracker includes custom lens profile support, provided by Mo-Sys directly, enabling even greater realism to your mixed reality content

- Expandable and upgradable –
   whether you have a green screen
   virtual studio, or LED wall virtual
   studio, StarTracker is the only tracking
   system you'll need
- VP Pro our feature rich direct integration to Unreal Engine for interfacing tracking and lens data. This is the first product from our Unreal Engine development team, several more products (Including patent pending technologies) will be announced shortly
- VP Studio Manager a remote system for setting up multiple StarTracker systems via a single interface. Makes set up and camera lens changes simple to administer









"We've used every kind of tracking system out there over the last few decades and the StarTracker has proven to be the most stable and reliable system."

Paul Lacombe, DisruptAR

"I just find that the StarTracker is extremely robust, once its set-up and calibrated, which doesn't take long, you come in in the morning and turn it on and it just knows where it is, it's just bullet proof and that's exactly what you want."

Jim Rider, Final Pixel

"We always recommend Mo-Sys because it is, in our opinion the most stable and the most rock solid camera tracking that you can get."

**Chris Tornow, Pfinix Creative Group** 

"We've been using the Mo-Sys StarTracker for almost 2-years now and its an incredibly stable system. You turn it on, and it works every time. I highly recommend them."

Tim Moore, Vu Technologies

# System information

### StarTracker

| Camera mounting Any (ped, Jib, steadicam, handheld) Lenses encoded External - Canon, Fujinon, film lenses Internal (Serial) - Canon & Fujinon Power consumption 20 W Voltage range 12-24 V DC LED ring wavelength 850 nm (IR) 455 nm (blue) on request Tracking server / PC Not required Display Not required for daily operation after initial setup  Studio space Winstudio size No lower limit Max studio size No lower limit Max studio size 100 x 100 m (no explicit limit) Min ceiling height 9-0.3 m from sensor* Max ceiling height 16+ m* Lighting restrictions No restrictions "with appropriately sized and spaced stars Number of studios/tracker No limit Tracking method Lens External encoders or VR lens readout Position/rotation Trackers/studio Tracker Satent confirmed: EP2962284A2 Protocol Mo-5ys F4 Connection UDP (IP) via RJ45 socket Genlock Analogue SDI, BnB, Tri-Level Min Delay 1 field (NTSC: 16.6 ms)  Star dots h = average floor-star height Diameter Between 1-15 cm depending on height Spacing Approx 1/10 floor-star height Minimum visible to track 11 (20+ well-spaced recommended) Configuration Ceiling or floor mounted  Accuracy Positional Approx 0.01 deg (nominal*) Angular Approx 0.01 deg (nominal*) Angular Approx 0.01 deg (nominal*) Angular Approx 0.01 deg (nominal*) Fine to find pose after tracking loss Drift accumulation No drift accumulation On Joy potical calibration None required  Dimensions Sensor Unit 7.5 x 7.5 x 7.5 cm Processor Unit 9 x 14 x 5 cm  Weight Sensor Unit 9.90g   | Axes tracked   | 6DOF: position & rotation 2 lens: (zoom, focus)                                       |
|--|--|---|
| Internal (Seria) - Canon & Fujinon  Power consumption  20 W  Voltage range  12-24 V DC  LED ring wavelength  850 nm (IR) 455 nm (Blue) on request  Tracking server / PC  Not required  Display  Not required for daily operation after initial setup  Studio space  Min studio size  No lower limit  Max studio size  No lower limit  Max studio size  No 100 x 100 m (no explicit limit)  Min ceiling height  -0.3 m from sensor*  Max ceiling height  16+ m*  Lighting restrictions  No restrictions  with appropriately sized and spaced stars  Number of studios/tracker  No limit  Number of trackers/studio  No limit  Tracking method  Lens  External encoders or VR lens readout  Position/rotation  Tracks randomly positioned retro-reflective stickers Patent confirmed: EP2962284A2  Protocol  Mo-Sys F4  Connection  UDP (IP) via RJ45 socket  Genlock  Analogue SDI, BnB, Tri-Level  Min Delay  1 field (NTSC: 16.6 ms)  Star dots  h = average floor-star height  Diameter  Between 1-15 cm depending on height  Spacing  Approx 1/10 floor-star height  Diameter  Between 1-15 cm depending on height  Spacing  Approx 1/10 floor-star height  Diameter  Between 1-15 cm depending on height  Spacing  Approx 0.03% of h (nominal*)  Angular  Approx 0.01 deg (nominal*)  16 bit  *As an optical system the accuracy depends on the distribution of the position of 30 space  Time to find pose after tracking loss  Firm to find pose after tracking loss  Processor Unit  Non erequired  Dimensions  Sensor Unit  Veight  Sensor Unit  300g  | Camera mounting  | Any (ped, jib, steadicam, handheld)   |
| Voltage range 12-24 V DC  LED ring wavelength 850 nm (IR) 455 nm (blue) on request  Tracking server / PC Not required for daily operation after initial setup  Studio space  Min studio size No lower limit  Max studio size 100 x 100 m (no explicit limit)  Min celling height 9-0.3 m from sensor*  Max ceiling height 16+ m*  Lighting restrictions No restrictions  Number of studios/tracker No limit  Number of studios/tracker No limit  Number of trackers/studio No limit  Tracking method  Lens External encoders or VR lens readout  Position/rotation Tracks randomly positioned retro-reflective stickers Patent confirmed: EP2962284A2  Protocol Mo-Sys F4  Connection UDP (IP) via RJ45 socket  Genlock Analogue SDI, BnB, Tri-Level  Min Delay 1 field (NTSC: 16.6 ms)  Star dots  h = average floor-star height  Diameter Between 1-15 cm depending on height  Spacing Approx 1/10 floor-star height  Minimum visible to track 11 (20+ well-spaced recommended)  Configuration Approx 0.03% of h (nominal*)  Angular Approx 0.01 deg (nominal*)  Angular Approx 0.01 deg (nominal*)  Angular Approx 0.01 deg (nominal*)  Price accurated the restriction of the distribution of stars visible to the sensor and their position in 30 space  Time to find pose after tracking loss 15 ensor Unit 7.5 x 7.5 x 7.5 cm  Processor Unit 7.5 x 7.5 x 7.5 cm  Processor Unit 9 x 14 x 5 cm  Weight  Sensor Unit 390g  | Lenses encoded   | External - Canon, Fujinon, film lenses<br>Internal (Serial) - Canon & Fujinon         |
| LED ring wavelength 455 nm (lR) 455 nm (blue) on request Tracking server / PC Not required Display Not required for daily operation after initial setup  Studio space Win studio size No lower limit Max studio size 100 x 100 m (no explicit limit) Min ceiling height 90.3 m from sensor* Max ceiling height 16+ m* Lighting restrictions No restrictions *with appropriately sized and spaced stars Number of studios/tracker No limit Number of trackers/studio No limit  Tracking method Lens External encoders or VR lens readout Position/rotation Tracks randomly positioned retro-reflective stickers Patent confirmed: EP2962284A2 Protocol Mo-Sys F4 Connection UDP (IP) via RJ45 socket Genlock Analogue SDI, BnB, Tri-Level Min Delay 1 field (NTSC: 16.6 ms)  Star dots h = average floor-star height Diameter Between 1-15 cm depending on height Spacing Approx 1/10 floor star height Minimum visible to track 11 (20+ well-spaced recommended) Configuration Reproduction Reproduction Reproduction Ceiling or floor mounted  Accuracy Positional Approx 0.019 deg (nominal*) Angular Approx 0.01 deg (nominal*) Angular Approx 0.01 deg (nominal*) Fincoding of the control of the position in 30 space Time to find pose after tracking loss 15 x 7.5 x 7.5 cm Processor Unit 9 x 14 x 5 cm  Weight Sensor Unit 390g   | Power consumption  | 20 W  |
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| Display         Not required for daily operation after initial setup           Studio space         No lower limit           Min studio size         No lower sensor*           Max ceiling height         >0.3 m from sensor*           Max ceiling height         16+ m*           Lighting restrictions         No restrictions           Number of studios/tracker         No limit           Number of studios/tracker         No limit           Tracking method         External encoders or VR lens readout           Lens         External encoders or VR lens readout           Position/rotation         Tracks randomly positioned retro-reflective stickers Patent confirmed: EP2962284A2           Protocol         Mo-Sys F4           Connection         UDP (IP) via RJ45 socket           Genlock         Analogue SDI, BnB, Tri-Level           Min Delay         1 field (NTSC: 16.6 ms)           Star dots         **           h = average floor-star height         **           Diameter         Between 1-15 cm depending on height           Spacing         Approx 1/10 floor-star height           Minimum visible to track         11 (20+ well-spaced recommended)           Configuration         Ceiling or floor mounted           Accuracy           Positional   | LED ring wavelength  |   |
| Studio space  Min studio size  | Tracking server / PC   | Not required  |
| Min studio size No lower limit  Max studio size 100 x 100 m (no explicit limit)  Min ceiling height 16+ m*  Lighting restrictions No restrictions *with appropriately sized and spaced stars  Number of studios/tracker No limit  Number of trackers/studio No limit  Tracking method  Lens External encoders or VR lens readout  Position/rotation Tracks randomly positioned retro-reflective stickers Patent confirmed: EP2962284A2  Protocol Mo-Sys F4  Connection UDP (P) via RJ45 socket  Genlock Analogue SDI, BnB, Tri-Level  Min Delay 1 field (NTSC: 16.6 ms)  Star dots  h = average floor-star height  Diameter Between 1-15 cm depending on height  Spacing Approx 1/10 floor-star height  Minimum visible to track 11 (20+ well-spaced recommended)  Configuration Ceiling or floor mounted  Accuracy  Positional Approx 0.03% of h (nominal*)  Angular Approx 0.01 deg (nominal*)  Encoding Approx 0.01 deg (nominal*)  Angular Approx 0.01 deg (nominal*)  Encoding Approx 0.01 deg (nominal*)  Fina count of find pose after tracking loss < 1 s (nominal)  Diff accumulation No drift accumulation  Daily optical calibration None required  Weight  Sensor Unit 7.5 x 7.5 x 7.5 cm  Processor Unit 19 x 14 x 5 cm  Weight  Sensor Unit 390g   | Display  | Not required for daily operation after initial setup                                  |
| Min studio size No lower limit  Max studio size 100 x 100 m (no explicit limit)  Min ceiling height 16+ m*  Lighting restrictions No restrictions *with appropriately sized and spaced stars  Number of studios/tracker No limit  Number of trackers/studio No limit  Tracking method  Lens External encoders or VR lens readout  Position/rotation Tracks randomly positioned retro-reflective stickers Patent confirmed: EP2962284A2  Protocol Mo-Sys F4  Connection UDP (P) via RJ45 socket  Genlock Analogue SDI, BnB, Tri-Level  Min Delay 1 field (NTSC: 16.6 ms)  Star dots  h = average floor-star height  Diameter Between 1-15 cm depending on height  Spacing Approx 1/10 floor-star height  Minimum visible to track 11 (20+ well-spaced recommended)  Configuration Ceiling or floor mounted  Accuracy  Positional Approx 0.03% of h (nominal*)  Angular Approx 0.01 deg (nominal*)  Encoding Approx 0.01 deg (nominal*)  Angular Approx 0.01 deg (nominal*)  Encoding Approx 0.01 deg (nominal*)  Fina count of find pose after tracking loss < 1 s (nominal)  Diff accumulation No drift accumulation  Daily optical calibration None required  Weight  Sensor Unit 7.5 x 7.5 x 7.5 cm  Processor Unit 19 x 14 x 5 cm  Weight  Sensor Unit 390g   | Studio space   |   |
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| *with appropriately sized and spaced stars  Number of studios/tracker No limit  Number of trackers/studio No limit  Tracking method  Lens External encoders or VR lens readout  Position/rotation Tracks randomly positioned retro-reflective stickers   | Max ceiling height   | 16+ m*  |
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| Positional Approx 0.03% of h (nominal*)  Angular Approx 0.01 deg (nominal*)  Encoding 16 bit  *As an optical system the accuracy depends on the distribution of stars visible to the sensor and their position in 3D space  Time to find pose after tracking loss <1 s (nominal)  Drift accumulation No drift accumulation  Daily optical calibration None required  Dimensions  Sensor Unit 7.5 x 7.5 x 7.5 cm  Processor Unit 19 x 14 x 5 cm  Weight  Sensor Unit 390g   | Configuration  | Ceiling or floor mounted  |
| Positional Approx 0.03% of h (nominal*)  Angular Approx 0.01 deg (nominal*)  Encoding 16 bit  *As an optical system the accuracy depends on the distribution of stars visible to the sensor and their position in 3D space  Time to find pose after tracking loss <1 s (nominal)  Drift accumulation No drift accumulation  Daily optical calibration None required  Dimensions  Sensor Unit 7.5 x 7.5 x 7.5 cm  Processor Unit 19 x 14 x 5 cm  Weight  Sensor Unit 390g   | Accuracy   |   |
| Angular Approx 0.01 deg (nominal*)  Encoding 16 bit  *As an optical system the accuracy depends on the distribution of stars visible to the sensor and their position in 3D space  Time to find pose after tracking loss <1 s (nominal)  Drift accumulation No drift accumulation  Daily optical calibration None required  Dimensions  Sensor Unit 7.5 x 7.5 x 7.5 cm  Processor Unit 19 x 14 x 5 cm  Weight  Sensor Unit 390g  | -  | Approx 0.03% of h (nominal*)  |
| Encoding 16 bit  *As an optical system the accuracy depends on the distribution of stars visible to the sensor and their position in 3D space  Time to find pose after tracking loss < 1 s (nominal)  Drift accumulation No drift accumulation  Daily optical calibration None required  Dimensions  Sensor Unit 7.5 x 7.5 x 7.5 cm  Processor Unit 19 x 14 x 5 cm  Weight  Sensor Unit 390g   | Angular  |   |
| Time to find pose after tracking loss < 1 s (nominal)  Drift accumulation No drift accumulation  Daily optical calibration None required  Dimensions  Sensor Unit 7.5 x 7.5 x 7.5 cm  Processor Unit 19 x 14 x 5 cm  Weight  Sensor Unit 390g  |  |   |
| Drift accumulation No drift accumulation Daily optical calibration None required  Dimensions Sensor Unit 7.5 x 7.5 x 7.5 cm Processor Unit 19 x 14 x 5 cm  Weight Sensor Unit 390g   | *As an optical system the accuracy depends on the distribution of stars visible to the sensor and their position in 3D space |   |
| Daily optical calibration     None required       Dimensions     Sensor Unit     7.5 x 7.5 x 7.5 cm       Processor Unit     19 x 14 x 5 cm       Weight       Sensor Unit     390g  | Time to find pose after tracking loss  | · · · · · · · · · · · · · · · · · · ·   |
| Dimensions           Sensor Unit         7.5 x 7.5 x 7.5 cm           Processor Unit         19 x 14 x 5 cm           Weight         390g  | Drift accumulation   | No drift accumulation   |
| Sensor Unit         7.5 x 7.5 x 7.5 cm           Processor Unit         19 x 14 x 5 cm           Weight         390g   | Daily optical calibration  | None required   |
| Processor Unit         19 x 14 x 5cm           Weight         Sensor Unit           390g   | Dimensions   |   |
| Weight<br>Sensor Unit 390g   | Sensor Unit  | 7.5 x 7.5 x 7.5cm   |
| Sensor Unit 390g   | Processor Unit   | 19 x 14 x 5cm   |
| Sensor Unit 390g   | Weight   |   |
|  |  | 390g  |
|  | Processor Unit   |   |

## For more information info@mo-sys.com | www.mo-sys.com

